

VECTOR CALCULUS

$$1. \quad \nabla = \frac{\partial}{\partial x} \bar{i} + \frac{\partial}{\partial y} \bar{j} + \frac{\partial}{\partial z} \bar{k}$$

2. If ϕ is a scalar point function then,

$$\begin{aligned} \nabla\phi &= \left(\frac{\partial}{\partial x} \bar{i} + \frac{\partial}{\partial y} \bar{j} + \frac{\partial}{\partial z} \bar{k} \right) \phi \\ &= \frac{\partial\phi}{\partial x} \bar{i} + \frac{\partial\phi}{\partial y} \bar{j} + \frac{\partial\phi}{\partial z} \bar{k} \end{aligned}$$

$\nabla\phi$ is called the gradient of ϕ (ϕ is a scalar function) and is denoted by $\text{grad } \phi$

i. e., $\text{grad } \phi = \nabla\phi$

$$3. \quad \text{i) } \nabla(f \pm g) = \nabla f \pm \nabla g$$

$$\text{ii) } \nabla(fg) = f\nabla g + g\nabla f$$

$$\text{iii) } \nabla C = 0 \text{ where } C \text{ is a constant}$$

iv) If $\vec{r} = x\bar{i} + y\bar{j} + z\bar{k}$ and $|\vec{r}| = r$ then,

$$\nabla r = \frac{\vec{r}}{r} = \hat{r}$$

$$\text{v) } \nabla r^n = nr^{n-2}\vec{r}$$

$$\text{vi) } \nabla f(r) = f'(r) \left(\frac{\vec{r}}{r} \right)$$

$$\text{vii) } \nabla(\log r) = \frac{\vec{r}}{r^2}$$

$$\text{viii) } \nabla f(r) \times \vec{r} = 0$$

4. The directional derivative of a scalar point function ϕ at the point (x, y, z) in the direction of a given vector \vec{a} is $\nabla\phi \cdot \frac{\vec{a}}{|\vec{a}|}$

5. The unit normal to the surface $\phi = 0$ at (x_1, y_1, z_1) is

$$\bar{n} = \frac{\nabla\phi(x_1, y_1, z_1)}{|\nabla\phi(x_1, y_1, z_1)|}$$

$$\text{ie., } \bar{n} = \frac{\nabla\phi}{|\nabla\phi|}$$

6. The directional derivative at a point P is maximum in the direction of the normal at P. The maximum directional derivative at P = $|\nabla\phi|$.

7. Angle between the surfaces $\phi_1 = 0$ and $\phi_2 = 0$ at (x_0, y_0, z_0) is $\cos \theta = \frac{\nabla\phi_1 \cdot \nabla\phi_2}{|\nabla\phi_1| |\nabla\phi_2|}$

8. Equation of tangent plane and normal plane for the surface $\phi = 0$ at a.

Equation of the tangent plane is $(\vec{r} - \vec{a}) \cdot \nabla\phi = 0$

Equation of the normal plane is $(\vec{r} - \vec{a}) \times \nabla\phi = 0$

9. Let \vec{F} be a vector valued function. Then,

$$\text{div } \vec{F} = \nabla \cdot \vec{F}$$

$$\text{curl } \vec{F} = \nabla \times \vec{F}$$

10. If $\vec{F} = F_1\bar{i} + F_2\bar{j} + F_3\bar{k}$ Then,

$\text{div } \vec{F}$

$$\begin{aligned} &= \left(\frac{\partial}{\partial x} \bar{i} + \frac{\partial}{\partial y} \bar{j} + \frac{\partial}{\partial z} \bar{k} \right) \cdot (F_1\bar{i} + F_2\bar{j} + F_3\bar{k}) \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \end{aligned}$$

$\text{Curl } \vec{F} = \nabla \times \vec{F}$

$$= \begin{vmatrix} \bar{i} & \bar{j} & \bar{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

11. $\text{div } \vec{F}$ is a scalar.

$\text{curl } \vec{F}$ is a vector quantity.

12. A vector \vec{F} is said to be solenoidal if $\nabla \cdot \vec{F} = 0$
i. e., $\text{div } \vec{F} = 0$

13. A vector \vec{F} is said to be irrotational if $\text{curl } \vec{F} = 0$

$$\text{i.e., } \nabla \times \vec{F} = 0$$

$$14. \quad \text{i) } \text{div} \left(\frac{\vec{r}}{r} \right) = \frac{2}{r}$$

$$\text{ii) } \text{div} (r^n \vec{r}) = (n+3)r^n$$

$$\text{iii) } \text{div} (r^n (\vec{a} \times \vec{r})) = 0$$

Where \vec{a} is a constant.

$$\text{iv) } \nabla \left(\frac{f(r)}{r} \vec{r} \right) = \frac{1}{r^2} \frac{d}{dr} (r^2 f(r))$$

$$15. \quad \text{i) } \nabla \times \vec{r} = 0$$

$$\text{ii) } \nabla \times (f(r)\vec{r}) = 0$$

$$\text{iii) } \nabla \times (r^n \vec{r}) = 0$$

16. If ϕ is a scalar function and \vec{F} is a vector function, then,

i) $\nabla \cdot \nabla \phi = \nabla^2 \phi$

ii) $\nabla \times (\nabla \phi) = 0$

i.e., curl grad $\phi = 0$

iii) $\nabla \cdot (\nabla \times \vec{F}) = 0$

iv) curl curl curl curl $\vec{F} = \nabla^4 \vec{F}$

v) $\nabla \times (\nabla r^n) = 0$

vi) $\nabla \cdot (\nabla r^n) = n(n+1)r^{n-2}$

vii) $\nabla \cdot (\phi \vec{F}) = (\nabla \phi) \cdot \vec{F} + \phi (\nabla \cdot \vec{F})$

viii) $\nabla \times (\phi \vec{F}) = (\nabla \phi) \times \vec{F} + \phi (\nabla \times \vec{F})$

ix) $\nabla \cdot (\vec{F} \times \vec{G}) = \vec{G} \cdot (\nabla \times \vec{F}) - \vec{F} \cdot (\nabla \times \vec{G})$

i.e., $\text{div} (\vec{F} \times \vec{G}) = \vec{G} \cdot \text{curl} \vec{F} - \vec{F} \cdot \text{curl} \vec{G}$

$\nabla \times (\nabla \times \vec{F}) = \nabla (\nabla \cdot \vec{F}) - \nabla^2 \vec{F}$

i.e., $\text{curl curl} \vec{F} = \nabla \text{div} \vec{F} - \nabla^2 \vec{F}$

Gauss Divergence Theorem:

Let \vec{F} be a vector point function, finite and differentiable in the region R bounded by a closed surface S, then the surface integral of the normal component of \vec{F} taken over S is equal to the integral of divergence of \vec{F} taken over V.

i.e., $\iint_S \vec{F} \cdot \hat{n} ds = \iiint_V \nabla \cdot \vec{F} dv$

1. **Deductions from Gauss divergence theorem:**

i) $\iiint_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dv = \iint_S (\phi \nabla \psi - \psi \nabla \phi) \cdot \hat{n} ds$ where, ϕ and ψ are scalar point functions.

ii) $\iiint_V \nabla \phi dv = \iint_S \hat{n} \cdot \phi ds$

iii) $\iiint_V \nabla \times \vec{F} dv = \iint_S \hat{n} \times \vec{F} ds$

2. **Cartesian form of Gauss divergence theorem:**

Let $\hat{n} = \cos \alpha \vec{i} + \cos \beta \vec{j} + \cos \gamma \vec{k}$

where, α , β and γ are the angles which \hat{n} makes with x, y, z axes respectively.

Let, $\vec{F} = F_1 \vec{i} + F_2 \vec{j} + F_3 \vec{k}$

Then,

$$\iiint_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dv \quad dx \, dy \, dz$$

$$= \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) ds$$

$$= \iint_S F_1 \, dydz + F_2 \, dzdx + F_3 \, dxdy$$

3. If S is a closed surface then

$$\iint_S \vec{r} \cdot \hat{n} \, ds = 3V$$

$$\iint_S \text{curl} \vec{F} \cdot \hat{n} \, ds = 0$$

$$\iint_S \nabla r^2 \cdot \hat{n} \, ds = 6V$$

$$\iint_S \frac{\vec{r} \cdot \hat{n}}{r^2} \, ds = \iiint_V \frac{dv}{r^2}$$

Stokes Theorem:

Let S be an open surface bounded by a closed curve C. Let \vec{F} be a vector point function defined on the surface S and \hat{n} is a unit outward normal at any point P on S.

Then, $\int_C \vec{F} \cdot d\vec{r} = \iint_S (\nabla \times \vec{F}) \cdot \hat{n} \, ds$

Deductions from Stokes Theorem:

i) $\int_C \vec{r} \cdot d\vec{r} = 0$

ii) $\int_C \phi \nabla \psi \cdot d\vec{r} = - \int_C \psi \nabla \phi \cdot d\vec{r}$

iii) $\int_C \phi \nabla \phi \cdot d\vec{r} = 0$

Green's theorem in plane:

Let R be a closed curve C. Let M and N be continuous functions of x and y having continuous partial derivatives in R. Then,

$$\oint_C M dx + N dy = \iint_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) dx \, dy$$

Where C is traversed in the anti-clock wise direction.

Green's theorem in plane (vector form)

Let $\vec{F} = M \vec{i} + N \vec{j}$

$\vec{r} = x \vec{i} + y \vec{j}$

$$d\vec{r} = dx \vec{i} + dy \vec{j}$$

Then, Green's theorem in vector form is

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R (\nabla \times \vec{F}) \cdot \mathbf{K} dR$$

Result:

Area bounded by any closed curve C is given by

$$\frac{1}{2} \oint_C (x dy - y dx)$$

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